Studies Concerning the Meaning of Computer Programs

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Introduction

In my three-year short research journey, I have studies three projects concerning the **meaning** of computer programs, specifically:

- How we model and understand programs;
- How we effectively **communicate** what we want computers to do in terms of programs with computers;
- How we **reason about** the behaviours of programs.

Three Conceptual Questions and Three Projects

- How to design a better abstraction mechanism that allows programmers to effectively express *what* they want a computer to do via some declarative yet accurate *specifications* instead of *how* a computer should accomplish a task via some concrete *implementations*?
 - Primrose: Selecting Container Data Types by Their Properties
- How do we characterise the relationship between the *syntax* and *semantics* of programming languages?
 - Shoggoth: A Formal Foundation for Strategic Rewriting
- How do we intuitively understand *distributed programs* using the same conceptual model as *monolithic programs*?
 - Oxidising Remote Procedural Calls

Primrose: Selecting Container Data Types by Their Properties

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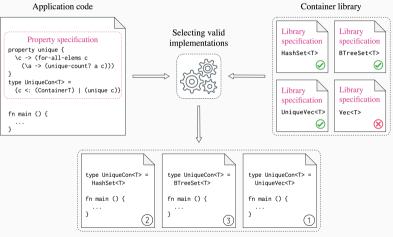
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- **Problem**: programmers have to choose a concrete implementation of a container type which is overly specific.
- **Drawbacks**: the chosen concrete implementation might not provide the desirable performance and portability of programs is limited.

The Design of Primrose

- Application programmers specify expected behaviours of a container in a program instead of how the container is implemented as **property specifications**;
 - A *syntactic property* specifies operations to interact with a container:
 - * We model it as a trait
 - * E.g., iterable elements can be accessed by an iterator
 - A *semantic property* specifies the desired behaviours of existing operations:
 - * We model it as a logic predicate refining a container type
 - * E.g., unique no duplicated elements in a container, it does not introduce any new operation
- Primrose, our pre-processing tool, selects all implementations from a container library where their **library specifications** match the desired property specifications;
- Primrose then chooses a *best* implementation (i.e., fastest, least memory consumption) for the program.

Overview of Primrose



Ranking valid implementations

Figure 1: The workflow of the Primrose selection tool

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Property Specifications and Library Specifications

Property specification

property unique { \c -> (for_all_elems c (\a -> (is_unique_count a c)))}
type UniqueCon<T> = {c impl (ContainerT) | (unique c)}

- Semantic property unique as refinement
- Syntactic property ContainerT as trait

Library specification

- Taking the form of a Hoare triple for each operation, defined w.r.t. a list model: {\$\phi\$} op(A) {\$\psi\$}
- The (absract) list model and the concrete implementation forms a **forward simulation**:
- Example: library specification for BTreeSet insertion:

 $\{x_{s_0}, x_{s_0} = \text{remove-duplicates (sort } x_{s_0} <)\}$ abs-insert $\{x_{s_0} \times x_s, x_s = \text{model-insert } x_{s_0} \times \}$

OD(A)

OD(C)

ia

 α^{-1} ; op(C) \subseteq op(A); α^{-1}

- Selecting container types in the library which implement specified syntactic properties (traits);
- Selecting container types of which the library specification match the semantic property specification, using the **Z3 SMT solver**:
 - check there is no contradiction between the semantic property and each precondition in the library specification;
 - assume the semantic property holds before each operation;
 - check if the resulting model list of each operation still satisfies the semantic property.

Summary of Our Contributions

- We show a **new application of refinement types** not—as previous work did—for verification purposes, but to raise the level of abstraction for developers and to improve the runtime performance of applications with container data types.
- We develop a **new methodology to specify container libraries**, amenable to our selection process, making use of existing formal methods work such as data abstraction and Hoare logic.
- We show the feasibility of Primrose, validate container implementations against specifications and evaluate the efficiency of the selection process.
- Paper available (<Programming> 2023): https://doi.org/10.22152/programming-journal.org/2023/7/11



Shoggoth: A Formal Foundation for Strategic Rewriting

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- Strategic rewriting languages provide programmers with **combinators** and **generic traversals** that allow them to:
 - control the application of rewrite rules
 - reuse rewrite rules
- Many application areas: program optimisation (ELEVATE [Hagedorn et al., 2020]), writing interpreter/compiler for DSLs (Spoofax/Stratego [Visser, 2001]) etc.
- However, there is a lack of formal treatment.

Atomic strategy

An atomic strategy is a *rewrite rule*:

 $add_{com} : a + b \rightsquigarrow b + a \quad add_{id} : 0 + a \rightsquigarrow a$

 $mult_{com} : a * b \rightsquigarrow b * a$

mapFusion : map f (map g xs) \rightsquigarrow map ($f \circ g$) xs

Composed strategy

 add_{com} ; add_{id} $add_{com} <+ mult_{com}$

repeat(mapFusion)

Strategy combinators

Strategy combinators compose strategies together and controls the application of atomic strategies:

s₁ ; s₂ sequential composition, apply s₁ then s₂
s₁ <+ s₂ left choice, if fail to apply s₁ then s₂
repeat(s) keep applying s until inapplicable

System S

System S [Visser and el Abidine Benaissa, 1998], the core calculus of strategic rewriting languages like ELEVATE [Hagedorn et al., 2020], Stratego [Visser, 2001] and Strafunski [Kaiser and Lämmel, 2009], contains **atomic strategies** (rewrite rules), **strategy combinators** which compose strategies and **traversals** that traverse the expression AST.

Expression

The expressions being rewritten by strategies are in the form of:

Expressions(
$$\mathbb{E}$$
) $e := Leaf \mid \bigcap_{e \in e}^{n}$

Syntax of Strategies

Strategy

Strategy(S) s := SKIP (Always succeeds) ABORT (Always results in error)	
atomic (Atomic strategy)	
$ s_1; s_2$ (Sequential composition)	
$ s_1 <+ s_2$ (Left choice)	
$ s_1 <+> t_2$ (Nondeterministic choice)	
one(s) (Apply s to one child, nondeterministic)	
<i>some(s)</i> (Apply <i>s</i> to as many children as possible, nondeterministic)	
all(s) (Apply s to all children, nondeterministic)	
X (Variable)	
$\mid \mu X.s \mid$ (Fixed-point operator)	

Importance of A Formal Understanding of Strategic Rewriting Languages

Strategies can go wrong

- Result in error an atomic strategy is not defined for certain expressions or strategies are not well composed, for example: *add_{com}*; *mult_{com}*
- Do not terminate for example: repeat(SKIP)
- Do not rewrite an expression into desired form

Existing formal work is not sufficient

- Big-step operational semantics of System S without modelling divergence [Visser and el Abidine Benaissa, 1998].
- Weakest preconditional calculus for System S using computational tree logic (CTL) [Kieburtz, 2001]. It has following issues:
 - $\circ~$ not expressive enough to reason about nondeterminism in traversals
 - problematic fixed-point operator construction
 - $\circ\;$ soundness of the calculus is not proven

Summary of Our Contributions

- We provide the formal semantics of System S, including both **denotational** and **operational** models.
 - Featuring **nondeterminism**, **errors**, and **divergence**.
 - Proving these two semantics models are equivalent via computational soundness and adequacy,
- We provide the weakest precondition calculus for the strategic rewriting language.
 - Proving its soundness w.r.t. the denotational semantics.
- We demonstrate how to use the weakest precondition calculus to **prove properties** of strategic rewriting.
- All formalised semantics and calculus as well as proofs are mechanised in Isabelle/HOL.
- Paper available (POPL 2024): https://doi.org/10.1145/3633211



Oxidising Remote Procedure Calls

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Motivation: Challenges in Existing Remote Procedure Call (RPC) Design

- In distributed computing, a remote procedure call (RPC) allows a method invocation to be executed on another computer on a shared network. Such a remote method invocation has the same coding as a local invocation, without the programmer explicitly coding the details for the remote interaction.
- It is hard to support **location transparency**, i.e., in most existing frameworks (e.g., Java RMI), remote invocations do not have **the same semantics** as local invocations.
- **Memory management** is hard in a distributed setting, for example, distributed garbage collection is complicated.

A New Remote Procedure Call Design: Universal Method Invocation

We design a **universal method invocation (UMI)** library in Rust, where our remote invocations have **the same semantics** as local invocations.



- It allows applications to be **migrated from a monolithic design** to a **distributed architecture** without massive changes to source code or the needs of high-level expertise in microservices.
- It gives support for **advanced optimisations** such as profile guided optimisation, which are not viable if changing the deployment requires extensive re-coding.

Why Rust?

- Rust is high-level system programming language which guarantees memory safety and prevents data races by its *ownership* rules for memory management and *borrow checker* for tracking object lifetime of all references in a program during compilation.
- Since Rust has semantics that guarantees memory safety, we can extend such guarantees to the distributed computing setting, allowing our UMI framework to provide safe remote method invocations.

Example: Deploying A Monolithic Program to Multiple Nodes

Key Idea: **location transparency** — a method invocation on a remote object preserves the semantics of the method invocation on a local object.

```
fn main() {
    #[gen_remote]
    struct A { arg: u32 }
                                          let a remote = remote!(addr, A::new(10));
    #[gen_remote]
                                          let a_local1 = A::new(1);
    impl A {
                                          let a_local2 = A::new(2);
      new(arg: u32) -> A {
                                          let mut a_local3 = A::new(3);
        A {arg: arg}
      }
                                          a_local1.fun_imm(&a_local2);
      fun_owned(&self, a: A) {...}
                                          a remote.fun imm(&a local2):
      fun_imm(&self, &a: A) {...} }
      fun_mut(&self, &mut a: A) {...}
      . . . . .
    3
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```

Argument Passing Semantics

Variable Binding Type	Passing Semantics
owned	pass by copy/ move
immutable reference	pass by reference
mutable reference	pass by mutable reference

Examples:

```
fn main() {
    ...
    a_remote.fun_owned(a_local1); // pass by copy/move
    a_remote.fun_imm(&a_local2); // pass by reference
    a_remote.fun_mut(&mut a_local3); // pass by mutable reference
}
```

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On a UMI server, we use a table with the same lifetime of the server to identify and manage local resources involved in remote computations.

- Rust **borrow checker** is generalised to work over the multiple nodes and handle remote allocation, access, modification and deallocation.
- If a variable is created locally, it will be put into the table once it is passed into a remote computation. The entry will not be removed (this table will ensure it is not deallocated) until the remote computation finishes.
- If a variable is created via a remote call, it will be put into table on creation. It will be deallocated when its remote owner decides to drop it.

- We provide a usable Rust implementation of the UMI framework.
- We formalise the **structural operational semantics** for a core calculus of monolithic and distributed Rust programs.
- We prove a **location transparency theorem**: With the UMI framework, when a monolithic program is deployed to multiple nodes, its semantics is preserved.
- The research results are currently under preparation to be submitted to a conference.

Finale

Three Years, Three Conceptual Questions and Three Projects

• How to design a better abstraction mechanism that allows programmers to effectively express *what* they want a computer to do via some declarative yet accurate *specifications* instead of *how* a computer should accomplish a task via some concrete *implementations*?

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Thank you!

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